

Understanding CLIP Robustness

Yuri Galindo, Fabio A. Faria*

Institute of Science and Technology, Universidade Federal de São Paulo, São José dos Campos, Brazil

yurioliveiragalindo@gmail.com, ffaria@unifesp.br

Abstract

Neural networks show a lack of robustness under adverse conditions, such as dealing with new datasets/distributions and adversarial perturbations. Some works in the literature, based on experiments with Resnet models trained on Imagenet, elect possible culprits such as the vulnerability to high frequency disturbances and dependence on non-robust features. Contrastive Language-Image Pre-training (CLIP) has been proposed as a new learning procedure which has improved robustness to new distributions but low robustness to adversarial examples. Therefore, CLIP presents an ideal opportunity for measuring how robust features and frequency sensitivity are associated with robustness to data shift. In this sense, we measure the vulnerability of CLIP model to high frequency perturbations, and perform image generation and inpainting tasks for assessment of robust features. In the performed experiments, the CLIP model is shown to be more robust to higher frequency perturbations and less robust to lower frequency perturbations, indicating a higher dependence on features with lower frequency. Finally, the images generated by CLIP were of low quality, indicating a lack of robust features.

1. Introduction

Deep Neural Networks achieve excellent classification results (over 90% accuracy in the Imagenet [15] dataset), even surpassing humans. However, these learning models do not perform well on new datasets and distributions, showing a considerable drop in performance [13].

Some works existing in literature have shown that these learning models are not robust in another adverse condition: the addition of specific perturbations (adversarial examples) [5]. Although these adversarial examples are mostly imperceptible by humans, they lead the models to make errors with high confidence score. Explaining how these mod-

els can surpass humans in some conditions and be so vulnerable in others is still an open research question.

An explanation for the existence of adversarial examples is that models learn non-robust features, i.e., information that is predictive but affected by small variations [7]. Models that are robust to adversarial attacks, on the other hand, rely on robust features, which are more aligned with human perception. Due to this alignment, robust models can be used for image synthesis tasks such as inpainting [12].

Yin *et al.* [14] have analyzed the robustness of Resnet models to different perturbations in terms of frequencies. The experiments showed that models which are robust to adversarial examples rely more on low-frequency information, and are more vulnerable to low-frequency perturbations such as contrast changes. Natural distribution shift such as the change of datasets was not studied.

These works presented interesting hypotheses, however the experiments were carried out using models based on Resnet [6], trained on the Imagenet [11] dataset. Therefore, it is not possible to know whether their findings hold for the general case of deep learning models trained on different ways.

Recently, the CLIP learning procedure (Contrastive Language-Image Pre-training) [10] has been proposed to achieve better robustness to natural distribution shifts. A CLIP model (ViT-B/32) is able to match the Resnet50 model performance on Imagenet without ever seeing any training examples, in a zero-shot fashion. This model has a non-convolutional architecture, relying instead on Transformers [9], and is trained on a dataset of 400 million image and text pairs, 400 times more examples than Imagenet [11]. It is also trained with a contrastive training objective, employing a text model in order to find the matching text and image pairs.

Due to its differences from previous models and its superior robustness to distribution shift, this CLIP model is the most suitable for verifying how the existing hypotheses for model robustness hold up in this case. Geirhos *et al.* [4] showed that CLIP is closer to human behavior in various aspects, including having less texture bias. Therefore, in this paper, we want to understand what it has changed in terms

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of frequency vulnerability and feature robustness.

2. Experimental Methodology

In this section, we performed the experiments using CLIP ViT-B/32 as a zero-shot classifier. It received the images as usual and text prompts in the format “a photo of a class”, for each possible class of the dataset. For the Imagenet100 dataset, in which each class corresponds to various names, we selected only the first given name. This procedure matches Resnet50 accuracy.

2.1. Frequency sensitivity

This experiment measures the accuracy of the model for perturbations of different frequencies. We build the “Fourier heat map” described in [14].

The Fourier basis vector $(i;j)$ is the image $U_{i,j}$ with norm 1 such that the discrete Fourier transform of the image, $DFT(U_{i,j})$, has the element $(i;j)$ different from 0 and all other elements equal to 0 [1]. For each image X of the validation set and each Fourier basis vector $(i;j)$, we obtain a perturbed version $\tilde{X}_{i,j}$ of the image for that specific frequency vector. This is described on the Equation 1, in which r is randomly chosen as -1 or 1 and v is the norm of the perturbation. As in [14], we used $v = 4.0$ for CIFAR10 and $v = 15.7$ for Imagenet.

$$\tilde{X}_{i,j} = X + rvU_{i,j} \quad (1)$$

We then measure the accuracy obtained by the model averaged over the images perturbed with this Fourier basis vector $(i;j)$, which corresponds to the point $(i;j)$ of our graph, centered on the origin. By obtaining the accuracy for the perturbation of all Fourier basis vectors, we can observe how the model behaves for perturbations of the whole frequency spectrum.

We performed this experiment on the test set of the CIFAR10 dataset [8], consisting of 10,000 images with dimensions of 32×32 divided in 10 categories, and on the Imagenet100 validation set, consisting of a subset of the Imagenet dataset composed of 100 randomly selected categories¹. The images have dimensions of 224×224 , with 50 examples per category. For the Imagenet experiments, we build a heatmap of size 63×63 , discarding the higher frequencies. This is done to replicate the heatmaps produced in the original paper [14] and better observe the frequencies used by the models. Experiments were built upon an existing implementation².

2.2. Robust Features

This experiment is qualitative, and aims to verify visually the quality of the features learned by the model. We fol-

¹kaggle.com/ambityga/imagenet100/metadata

²github.com/gatheluck/FourierHeatmap

low the experimental methodology for inpainting and image generation described in [12]. Experiments were built upon the official implementation³

For image generation, first we obtain the mean and standard deviation of the pixels of the images of the class of interest y . Then, we sample pixels assuming a normal distribution with the observed mean and deviation. Now, we apply projected gradient descent (PGD) in order to maximize the probability assigned by the model to the modified image X' while keeping the norm of the perturbation as less than $\epsilon = 40$.

The Equation 2 shows the minimization objective, in which \mathcal{L} is the Cross Entropy loss and x_0 is the image sampled by the class distribution \mathcal{G}_y . C refers to the classification model, which takes an image as input and outputs class probabilities.

$$x = \underset{s.t. \|x' - x_0\|_2 \leq \epsilon}{\arg \min_{x'}} \mathcal{L}(C(x'); y); \quad x_0 \sim \mathcal{G}_y \quad (2)$$

For the inpainting experiment, we randomly assign a region of the image of size 60×60 , and substitute it by the mean of the pixels of the region, over each channel. Now, we apply PGD in order to maximize the probability assigned by the model while minimizing the pixels altered outside the region and keeping the norm of the perturbation as less than $\epsilon = 21.6$.

Equation 3 shows the minimization objective, in which ϵ is a constant, m is the mask matrix which is equal to 1 on the affected region and 0 elsewhere. \odot corresponds to element-wise multiplication. Other symbols have the same meaning as in Equation 2. In our experiments, $\epsilon = 10$.

$$x_I = \underset{s.t. \|x' - x_0\|_2 \leq \epsilon}{\arg \min_{x'}} \mathcal{L}(C(x'); y) + \|(x - x') \odot (1 - m)\|_2 \quad (3)$$

3. Results and Discussion

This section presents the experiments performed in this paper and discusses the achieved results.

3.1. Frequency sensitivity

On both CIFAR10 and Imagenet100 datasets, CLIP ViT-B/32 displayed a different behavior from what was previously observed in the Resnet50 model. We found that CLIP is less robust than the Resnet50 to perturbations in the low-frequency domain, and more robust to perturbations in the highest frequencies. This can mean that CLIP relies more on low-frequency information, when compared to Resnet models [14].

In Figure 1, we can see the error rates of both models for the CIFAR10 dataset. We can see that the Resnet isn't affected by the lowest frequency perturbations, shown in the

³github.com/MadryLab/robustness_applications

blue circle in the center. However, it is affected by perturbations of the highest frequencies, shown by the red on the extremities. CLIP, on the other hand, shows higher vulnerability on the lowest frequencies and less vulnerability on the highest frequencies.

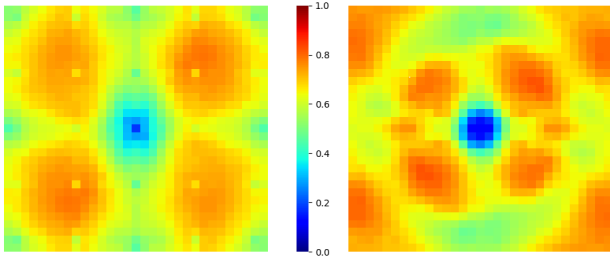


Figure 1. Error rates of the CLIP ViT-B/32 (left) and Resnet50 (right) models for perturbations over the frequency spectrum on the CIFAR10 dataset.

Figure 2 displays the error rates on Imagenet100, in which we can see more clearly the low frequency bias of CLIP model. CLIP model maintains high error rates in the lowest frequencies up to a point, which then decreases for higher frequencies. The Resnet50, on the other hand, shows low error for the lowest frequencies (displayed on a blue circle in the center) and high error on the other frequency regions, including close to the extremities – the highest considered frequencies.

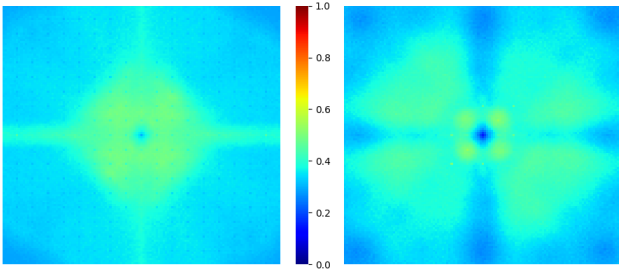


Figure 2. Error rates of the CLIP ViT-B/32 (left) and Resnet50 (right) models for perturbations of various frequencies on the Imagenet100 dataset. The images are cropped with 63×63 size, centered at the lowest frequency on the Fourier domain.

3.2. Robust features

In the inpainting experiment, the robust model described in [12] was capable of finding meaningful reconstructions. The images generated with the robust model were semantically similar to the images before corruption, and were perceptually plausible to humans even in the case of mistakes.

The CLIP model, however, does not reconstruct the corrupted images. As showcased in Fig. 3, CLIP model barely changes the corrupted patches. The alterations are limited

to almost imperceptible squiggles. To the model, however, these alterations are highly accurate and even capable of changing a wrong classification to the correct class. The inpainting loss (3), which is based on the probability assigned by the model for each image, decreased from 3.8 to $2e-4$.

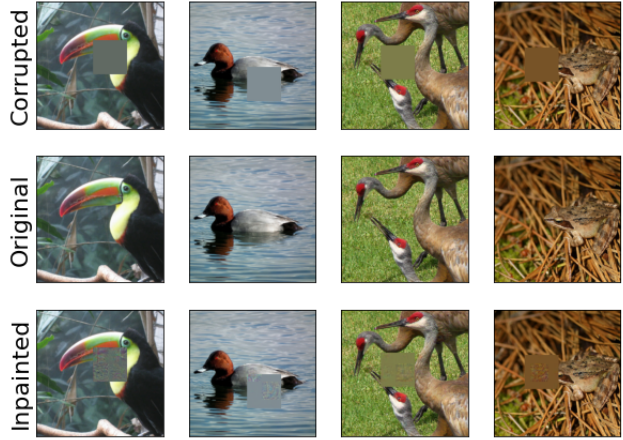


Figure 3. Inpainting task, performed using the CLIP ViT-B/32 model.

The image generation experiment is illustrated on Fig. 4, and obtained similar results. The images generated by the robust models in [12], while not realistic, showcased perceptually relevant features such as feathers, eyes, fur and noses. The images generated by CLIP model, on the other hand, do not display such features. Any similarity to the original class is due to the pixel sampling process, with the final result looking like incomprehensible noise. To the model, however, these images have high likelihood of pertaining to the correct class. The generation loss (2), based on the probability assigned by the model, decreased from 3.5 on the raw sampled pixels to $3e-5$ on the final images.

4. Discussion

In the first experiment, we observed differences between the Fourier heatmap of a Resnet and CLIP models. We observed that in relation to the Resnet model, the CLIP model has lower robustness to low frequency perturbations and higher robustness to high frequency perturbations. This can mean that this CLIP model depends on lower frequencies than the Resnet model, and as so is more affected by perturbations in these frequencies [14].

This indicates that robustness to natural distribution shifts might be associated to dependency on lower frequency information and higher robustness in high frequency domains. Since the CLIP model is robust to high frequency perturbations and is still vulnerable to adversarial attacks [2, 3], this is also further evidence that adversarial attacks are not exclusively a high frequency phe-

